

## Invariant Submanifold Of $\tilde{\psi}$ (6,4,2) Structure Manifold

Lakhan Singh

Shailendra Kumar Gautam

Department of Mathematics, D.J. College, Baraut, Baghpat  
(U.P.), India

Eshan College of Engineering, Mathura (UP), India

**Abstract:** In this paper, we have studied various properties of a  $\tilde{\psi}$  (6,4,2) structure manifold and its invariant submanifold. Under two different assumptions, the nature of induced structure  $\psi$ , has also been discussed.

**Keywords:** Invariant submanifold, Nijenhuis tensor, projection operators and complementary distributions.

### I. INTRODUCTION

Let  $V^m$  be a  $C^\infty$   $m$ -dimensional Riemannian manifold imbedded in a  $C^\infty$   $n$ -dimensional Riemannian manifold  $M^n$ , where  $m < n$ . The imbedding being denoted by

$$f : V^m \longrightarrow M^n$$

Let  $B$  be the mapping induced by  $f$  i.e.  $B = df$

$$df : T(V) \longrightarrow T(M)$$

Let  $T(V, M)$  be the set of all vectors tangent to the submanifold  $f(V)$ . It is well known that

$$B : T(V) \longrightarrow T(V, M)$$

is an isomorphism. The set of all vectors normal to  $f(V)$  forms a vector bundle over  $f(V)$ , which we shall denote by  $N(V, M)$ . We call  $N(V, M)$  the normal bundle of  $V^m$ . The vector bundle induced by  $f$  from  $N(V, M)$  is denoted by  $N(V)$ . We denote by  $C : N(V) \longrightarrow N(V, M)$  the natural isomorphism and by  $\eta_s^r(V)$  the space of all  $C^\infty$  tensor fields of type  $(r, s)$  associated with  $N(V)$ . Thus  $\zeta_0^0(V) = \eta_0^0(V)$  is the space of all  $C^\infty$  functions defined on  $V^m$  while an element of  $\eta_0^1(V)$  is a  $C^\infty$  vector field normal

to  $V^m$  and an element of  $\zeta_0^1(V)$  is a  $C^\infty$  vector field tangential to  $V^m$ .

Let  $\bar{X}$  and  $\bar{Y}$  be vector fields defined along  $f(V)$  and  $\tilde{X}, \tilde{Y}$  be the local extensions of  $\bar{X}$  and  $\bar{Y}$  respectively. Then  $[\tilde{X}, \tilde{Y}]$  is a vector field tangential to  $M^n$  and its restriction  $[\tilde{X}, \tilde{Y}]/f(V)$  to  $f(V)$  is determined independently of the choice of these local extension  $\tilde{X}$  and  $\tilde{Y}$ . Thus  $[\bar{X}, \bar{Y}]$  is defined as

$$(1.1) \quad [\bar{X}, \bar{Y}] = [\tilde{X}, \tilde{Y}]/f(V)$$

Since  $B$  is an isomorphism

$$(1.2) \quad [BX, BY] = B[X, Y] \quad \text{for all } X, Y \in \zeta_0^1(V)$$

Let  $\bar{G}$  be the Riemannian metric tensor of  $M^n$ , we define  $g$  and  $g^*$  on  $V^m$  and  $N(V)$  respectively as

$$(1.3) \quad g(X_1, X_2) = \bar{G}(BX_1, BX_2) f, \quad \text{and}$$

$$(1.4) \quad g^*(N_1, N_2) = \bar{G}(CN_1, CN_2)$$

For all  $X_1, X_2 \in \zeta_0^1(V)$  and  $N_1, N_2 \in \eta_0^1(V)$

It can be verified that  $g$  and  $g^*$  are the induced metrics on  $V^m$  and  $N(V)$  respectively.

Let  $\tilde{\nabla}$  be the Riemannian connection determined by  $\tilde{G}$  in  $M^n$ , then  $\tilde{\nabla}$  induces a connection  $\nabla$  in  $f(V)$  defined by

$$(1.5) \quad \nabla_{\bar{X}}\bar{Y} = \tilde{\nabla}_{\bar{X}}\tilde{Y}/f(V)$$

where  $\bar{X}$  and  $\bar{Y}$  are arbitrary  $C^\infty$  vector fields defined along  $f(V)$  and tangential to  $f(V)$ .

Let us suppose that  $M^n$  is a  $C^\infty \tilde{\psi}(6,4,2)$  structure manifold with structure tensor  $\tilde{\psi}$  of type (1,1) satisfying

$$(1.6) \quad \tilde{\psi}^6 + \tilde{\psi}^4 + \tilde{\psi}^2 = 0$$

Let  $\tilde{l}$  and  $\tilde{m}$  be the complementary distributions corresponding to the projection operators

$$(1.7) \quad \tilde{l} = \tilde{\psi}^6, \quad \tilde{m} = I - \tilde{\psi}^6$$

where I denotes the identity operator.

From (1.6) and (1.7), we have

$$(1.8) \quad (a) \quad \tilde{l} + \tilde{m} = I \quad (b) \quad \tilde{l}^2 = \tilde{l} \\ (c) \quad \tilde{m}^2 = \tilde{m} \quad (d) \quad \tilde{l}\tilde{m} = \tilde{m}\tilde{l} = 0$$

Let  $D_l$  and  $D_m$  be the subspaces inherited by complementary projection operators l and m respectively.

We define

$$D_l = \{X \in T_p(V) : lX = X, mX = 0\}$$

$$D_m = \{X \in T_p(V) : mX = X, lX = 0\}$$

$$\text{Thus } T_p(V) = D_l + D_m$$

$$\text{Also } \text{Ker } l = \{X : lX = 0\} = D_m$$

$$\text{Ker } m = \{X : mX = 0\} = D_l$$

at each point  $p$  of  $f(V)$ .

## II. INVARIANT SUBMANIFOLD OF $\tilde{\psi}(6,4,2)$ STRUCTURE MANIFOLD

We call  $V^m$  to be invariant submanifold of  $M^n$  if the tangent space  $T^p(f(V))$  of  $f(V)$  is invariant by the linear mapping  $\tilde{\psi}$  at each point  $p$  of  $f(V)$ . Thus

$$(2.1) \quad \tilde{\psi}BX = B\psi X, \text{ for all } X \in \zeta_0^1(V), \text{ and } \psi \text{ being a (1,1) tensor field in } V^m.$$

**THEOREM (2.1):** Let  $\tilde{N}$  and  $N$  be the Nijenhuis tensors determined by  $\tilde{\psi}$  and  $\psi$  in  $M^n$  and  $V^m$  respectively, then

$$(2.2) \quad \tilde{N}(BX, BY) = BN(X, Y), \text{ for all } X, Y \in \zeta_0^1(V)$$

**PROOF:** We have, by using (1.2) and (2.1)

$$(2.3) \quad \tilde{N}(BX, BY) = [\tilde{\psi}BX, \tilde{\psi}BY] + \tilde{\psi}^2[BX, BY] - \tilde{\psi}[\tilde{\psi}BX, BY] - \tilde{\psi}[BX, \tilde{\psi}BY]$$

$$= [B\psi X, B\psi Y] + \tilde{\psi}^2B[X, Y] - \tilde{\psi}[B\psi X, BY] - \tilde{\psi}[BX, B\psi Y] \\ = B[\psi X, \psi Y] + B\psi^2[X, Y] - \tilde{\psi}B[\psi X, Y] - \tilde{\psi}B[X, \psi Y] \\ = B\{[\psi X, \psi Y] + \psi^2[X, Y] - \psi[\psi X, Y] - \psi[X, \psi Y]\} \\ = BN(X, Y)$$

## III. DISTRIBUTION $\tilde{M}$ NEVER BEING TANGENTIAL TO $f(V)$

**THEOREM (3.1):** if the distribution  $\tilde{M}$  is never tangential to  $f(V)$ , then

$$(3.1) \quad \tilde{m}(BX) = 0 \text{ for all } X \in \zeta_0^1(V) \text{ and the induced structure } \psi \text{ on } V^m \text{ satisfies}$$

$$(3.2) \quad \psi^4 + \psi^2 + I = 0. \text{ Thus } \psi \text{ is (4,2,0)}$$

**PROOF:** if possible  $\tilde{m}(BX) \neq 0$ . From (2.1) We get

$$(3.3) \quad \tilde{\psi}^2BX = B\psi^2 X; \text{ etc from (1.7) and (3.3)}$$

$$\tilde{m}(BX) = (I - \tilde{\psi}^6)BX \\ = (I + \tilde{\psi}^2 + \tilde{\psi}^4)BX \\ = BX + B\psi^2 X + B\psi^4 X$$

$$(3.4) \quad \tilde{m}(BX) = B(X + \psi^2 X + \psi^4 X)$$

This relation shows that  $\tilde{m}(BX)$  is tangential to  $f(V)$  which contradicts the hypothesis. Thus  $\tilde{m}(BX) = 0$ . Using this result in (3.4) and remembering that  $B$  is an isomorphism, We get

$$(3.5) \quad \psi^4 + \psi^2 + I = 0$$

**THEOREM (3.2):** Let  $\tilde{M}$  be never tangential to  $f(V)$ , then

$$(3.6) \quad \tilde{N}_{\tilde{m}}(BX, BY) = 0$$

**PROOF:** We have

$$(3.7) \quad \tilde{N}_{\tilde{m}}(BX, BY) = [\tilde{m}BX, \tilde{m}BY] + \tilde{m}^2[BX, BY] - \tilde{m}[\tilde{m}BX, BY] - \tilde{m}[BX, \tilde{m}BY]$$

Using (1.2), (1.8) (c) and (3.1), we get (3.6).

**THEOREM (3.3):** Let  $\tilde{M}$  be never tangential to  $f(V)$ , then

$$(3.8) \quad \tilde{N}_{\tilde{l}}(BX, BY) = 0$$

**PROOF:** We have

$$(3.9) \quad \tilde{N}_{\tilde{l}}(BX, BY) = [\tilde{l}BX, \tilde{l}BY] + \tilde{l}^2[BX, BY] - \tilde{l}[\tilde{l}BX, BY] - \tilde{l}[BX, \tilde{l}BY]$$

Using (1.2), (1.8) (a), (b) and (3.1) in (3.9); we get (3.8)

**THEOREM (3.4):** Let  $\tilde{M}$  be never tangential to  $f(V)$ .

Define

$$(3.10) \quad \tilde{H}(\tilde{X}, \tilde{Y}) = \tilde{N}(\tilde{X}, \tilde{Y}) - \tilde{N}(\tilde{m}\tilde{X}, \tilde{Y}) - \tilde{N}(\tilde{X}, \tilde{m}\tilde{Y}) \\ + \tilde{N}(\tilde{m}\tilde{X}, \tilde{m}\tilde{Y})$$

For all  $\tilde{X}, \tilde{Y} \in \zeta_0^1(M)$ , then

$$(3.11) \tilde{H}(BX, BY) = BN(X, Y)$$

PROOF: Using  $\tilde{X} = BX$ ,  $\tilde{Y} = BY$  and (2.2), (3.1) in (3.10) We get (3.11).

#### IV. DISTRIBUTION $\tilde{M}$ ALWAYS BEING TANGENTIAL TO $f(V)$

THEOREM (4.1): Let  $\tilde{M}$  be always tangential to  $f(V)$ , then

$$(4.1) (a) \tilde{m}(BX) = BmX \quad (b) \tilde{l}(BX) = BlX$$

PROOF: from (3.4), We get (4.1) (a). Also

$$(4.2) l = \psi^6$$

$$lX = \psi^6 X$$

$$(4.3) BlX = B\psi^6 X$$

Using (2.1) in (4.3)

$$(4.4) BlX = \tilde{\psi}^6 BX = \tilde{l}(BX),$$

which is (4.1) (b).

THEOREM (4.2): Let  $\tilde{M}$  be always tangential to  $f(V)$ , then  $l$  and  $m$  satisfy

$$(4.5) (a) l + m = I \quad (b) lm = ml = 0 \quad (c) l^2 = l \quad (d) m^2 = m.$$

PROOF: Using (1.8) and (4.1) We get the results.

THEOREM (4.3): If  $\tilde{M}$  is always tangential to  $f(V)$ , then

$$(4.6) \psi^6 + \psi^4 + \psi^2 = 0$$

PROOF: From (2.1)

$$(4.7) \tilde{\psi}^6 BX = B\psi^6 X$$

Using (1.6) in (4.7)

$$(-\tilde{\psi}^4 - \tilde{\psi}^2) BX = B\psi^6 X$$

$$-B\psi^4 X - B\psi^2 X = B\psi^6 X$$

$$\text{Or } \psi^6 + \psi^4 + \psi^2 = 0 \text{ which is (4.6)}$$

THEOREM (4.4): If  $\tilde{M}$  is always tangential to  $f(V)$  then as in (3.10)

$$(4.8) \tilde{H}(BX, BY) = BH(X, Y)$$

PROOF: from (3.10) we get

$$(4.9) \tilde{H}(BX, BY) = \tilde{N}(BX, BY) - \tilde{N}(\tilde{m}BX, BY) - \tilde{N}(BX, \tilde{m}BY) + \tilde{N}(\tilde{m}BX, \tilde{m}BY)$$

Using (4.1) (a) and (2.2) in (4.9) we get (4.8).

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